

香港中文大學

The Chinese University of Hong Kong

# CSCI2510 Computer Organization Lecture 13: Basic Input & Output

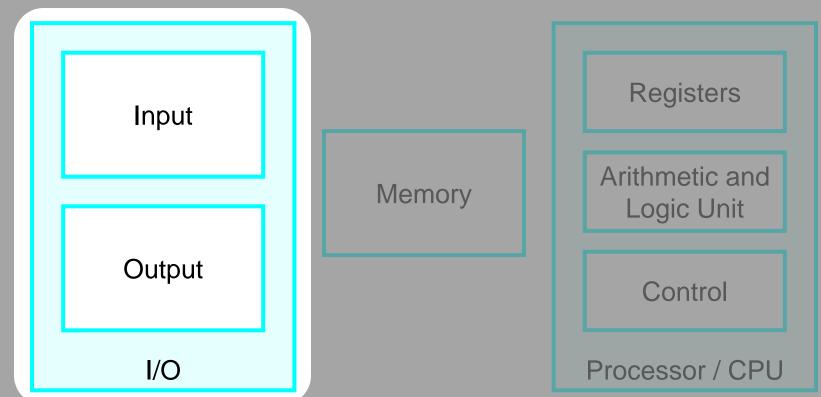
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COMPUTER ORGANIZATION AND EMBEDDED SYSTEMS

Reading: Chap. 3

#### Basic Functional Units of a Computer



- Input: accepts coded information from human operators.
- **Memory**: stores the received information for later use.
- **Processor**: executes the instructions of a program stored in the memory.
- **Output**: sends back to the outside world.
- **Control**: coordinates all of these actions. CSCI2510 Lec06: Memory Hierarchy

#### Outline

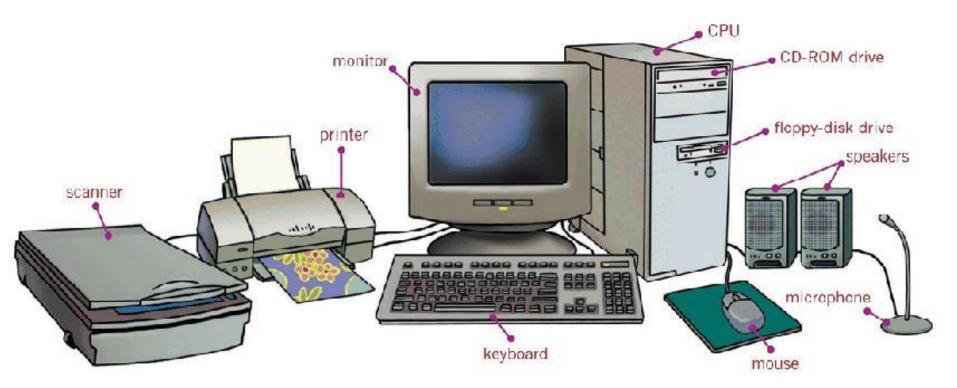


- Accessing I/O Devices
  - Memory-Mapped I/O
  - I/O Device Interface
  - Program-Controlled I/O
  - Interrupts
- Storage I/O
  - Hard Disk Drive (HDD)
  - Solid State Drive (SSD)

# Input and Output Units (I/O)



- Computers should have the ability to exchange digital and analog information with a wide range of devices.
- The collective term input/output (I/O) units: input units, output units, disk drives, etc.



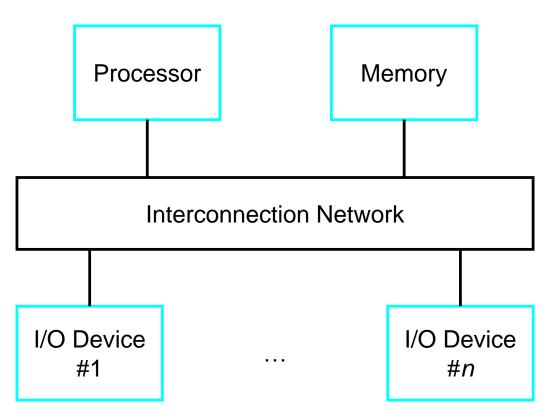
https://norizman.wordpress.com/notes/

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## Accessing I/O Devices



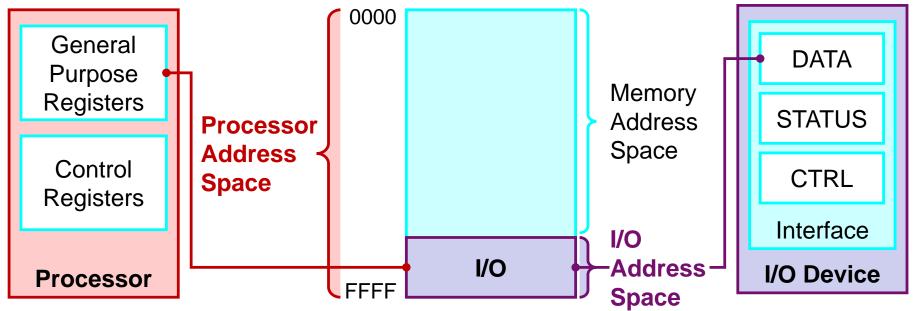
- The components of a computer system communicate with each other through an interconnection network.
  - The network enables the information transfer between the processor, the memory unit, and a number of I/O devices.



### Memory-Mapped I/O



- The idea of using addresses to access (i.e. load/store) memory can be extended to deal with the I/O devices.
  - I/O devices consist of addressable locations, like memory.
  - E.g., Load R2, DATA, Store R2, DATA.
- Memory-Mapped I/O: I/O devices and the memory share the same address space of the processor.

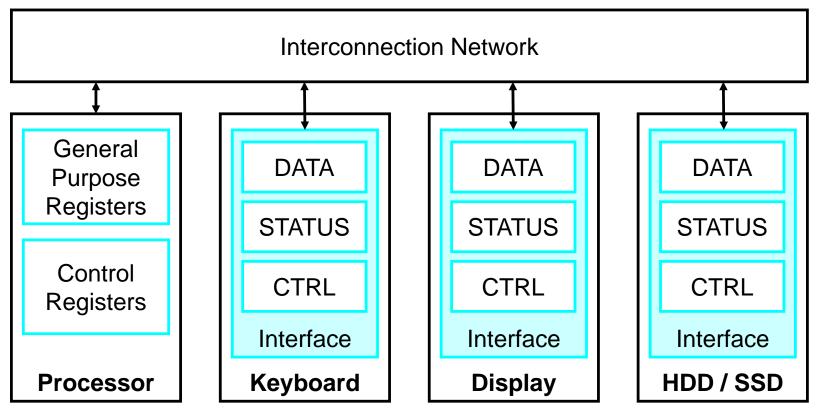


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### **I/O Device Interface**



- An I/O device is connected to the interconnection network via the device interface.
  - The interface has some registers, accessible by the CPU, for data transfer, exchange of status, and control.



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## **Program-Controlled I/O**



- Let us begin with two most essential I/O devices for human-computer interaction—keyboard and display.
  - Consider a task that reads characters typed on a keyboard, stores these data in the memory, and displays the same characters on a display screen.
    - A processor executes billions of instructions per second.
    - Characters can be transmitted to and displayed on the display, typically several thousand characters per second.
    - The typing speed of the user is few characters per second.
- **Program-Controlled I/O**: Use a program to perform all functions needed to realize the desired action.
  - The speed difference in speed between the CPU and I/O devices creates need to be synchronized.

#### An Example of a RISC-Style I/O Program

• The program reads, stores, and displays a line of characters typed at the keyboard.

| Move                | R2, #LOC  | Initialize pointer register R2 to point to the<br>address of the first location in main memory<br>where the characters are to be stored.   |
|---------------------|---|--|
| MoveByte            | R3, #CR   | Load ASCII code for Carriage Return into R3.   |
| LoadByte            | R4, KBD_STATUS  | Wait for a character to be entered.  |
| And                 | R4, R4, #2  | Check the KIN flag.  |
| Branch_if_[R4]=0    | READ  |  |
| LoadByte            | R5, KBD_DATA  | Read the character from KBD_DATA   |
|                     |   | (this clears KIN to 0).  |
| StoreByte           | R5, (R2)  | Write the character into the main memory and   |
| Add                 | R2, R2, #1  | increment the pointer to main memory.  |
| LoadByte            | R4, DISP_STATUS   | Wait for the display to become ready.  |
| And                 | R4, R4, #4  | Check the DOUT flag.   |
| Branch_if_[R4]=0    | ECHO  |  |
| StoreByte           | R5, DISP_DATA   | Move the character just read to the display<br>buffer register (this clears DOUT to 0).  |
| Branch_if_[R5]≠[R3] | READ  | Check if the character just read is the<br>Carriage Return. If it is not, then<br>branch back and read another character.  |
|                     | MoveByte<br>LoadByte<br>And<br>Branch_if_[R4]=0<br>LoadByte<br>StoreByte<br>Add<br>LoadByte<br>And<br>Branch_if_[R4]=0<br>StoreByte | MoveByteR3, #CRLoadByteR4, KBD_STATUSAndR4, R4, #2Branch_if_[R4]=0READLoadByteR5, KBD_DATAStoreByteR5, (R2)AddR2, R2, #1LoadByteR4, DISP_STATUSAndR4, R4, #4Branch_if_[R4]=0ECHOStoreByteR5, DISP_DATA |

# Interrupts (1/2)

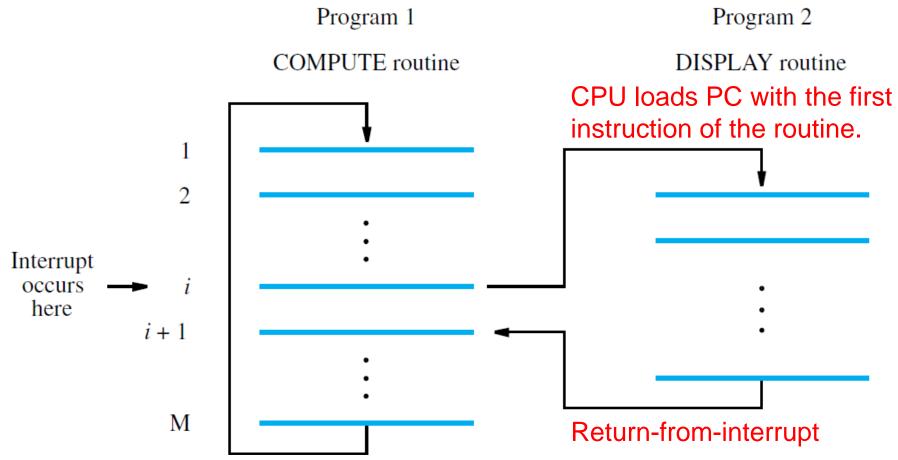


- The previous program enters a wait loop in which it repeatedly tests the device status.
  - During this period, the processor is not performing any useful computation.
  - There are many situations where other tasks can be performed while waiting for an I/O device to become ready.
- To allow this to happen, we can arrange for the I/O device to alert the processor when it becomes ready.
  - It can do so by sending a hardware signal called an interrupt request to the processor.
  - The routine executed in response to an interrupt request is called the interrupt-service routine.

# Interrupts (2/2)



 Assume an interrupt arrives during instruction *i* of the COMPUTE routine, and the DISPLAY routine is the interrupt-service routine.



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## Storage I/O

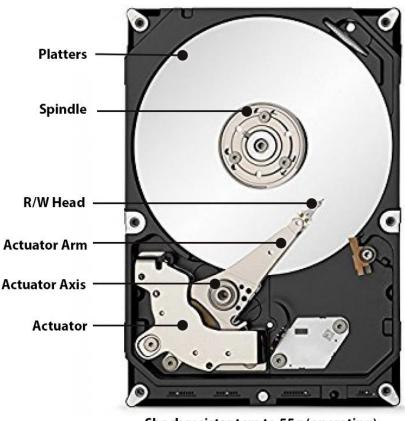


The most common two types: HDD and SSD

HDD

3.5"

#### CHEAPER PER GB LARGER STORAGE

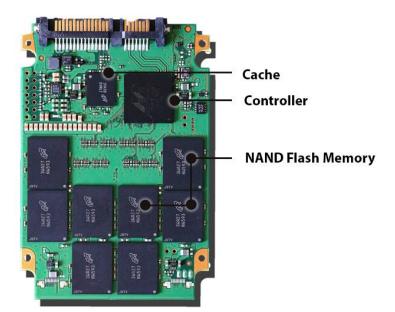


Shock resistant up to 55g (operating) Shock resistant up to 350g (non-operating)

https://www.backblaze.com/blog/ssd-vs-hdd-future-of-storage/

#### BETTER PERFORMANCE SHOCK RESISTANCE MORE ENERGY EFFICIENT

SSD 2.5"

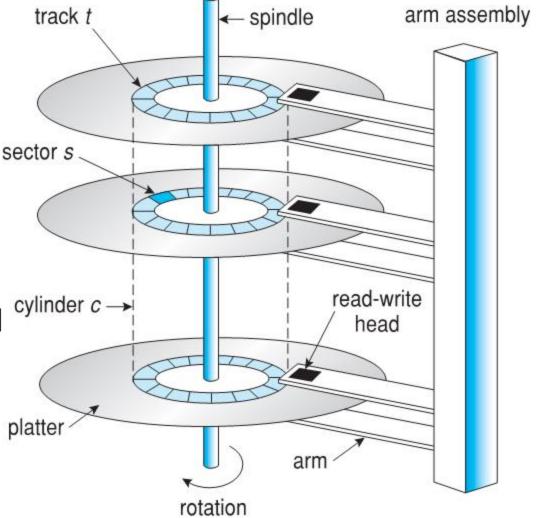


Shock resistant up to 1500g (operating and non-operating)

# Hard Disk Drive (HDD)



- HDD provides bulk of storage for modern computers.
- Digital data can be stored in any sector s of any track t on any disk platter p.
- HDD Seeking Time:
  - Time to move disk arm to desired cylinder, and
  - Time to rotate the disk head to the sector.
    - Platter rotates at 60 to 250 times per second.



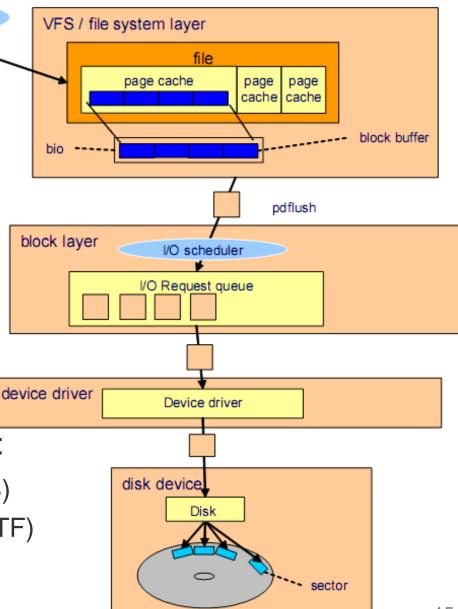
# **I/O Scheduling for HDDs**

User process

write()

- I/O Scheduling
  - Accesses to the HDD should be scheduled.
  - The goal is to <u>minimize the</u> <u>total seek time</u> for a given set of accesses.
  - The operating system is responsible for the I/O scheduling.
  - There're many different
    HDD scheduling algorithms:
    - First Come First Serve (FCFS)
    - Shortest Seek Time First (SSTF)
    - SCAN (a.k.a. Elevator)

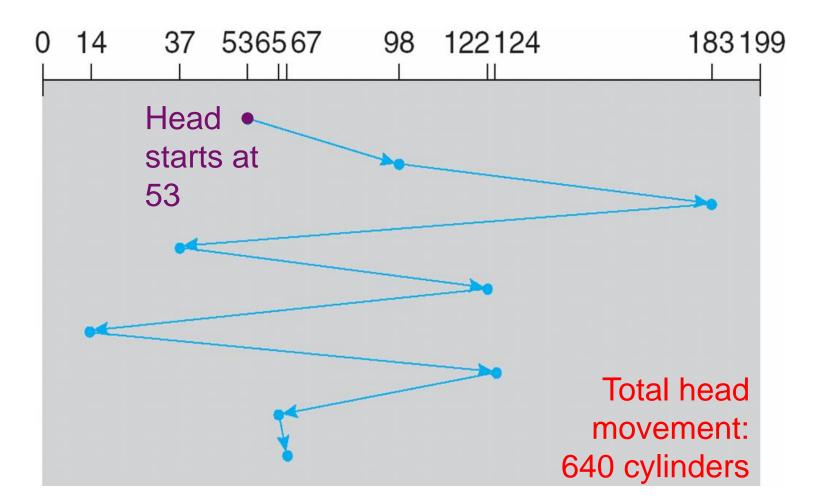
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#### First Come First Serve (FCFS) Algo.

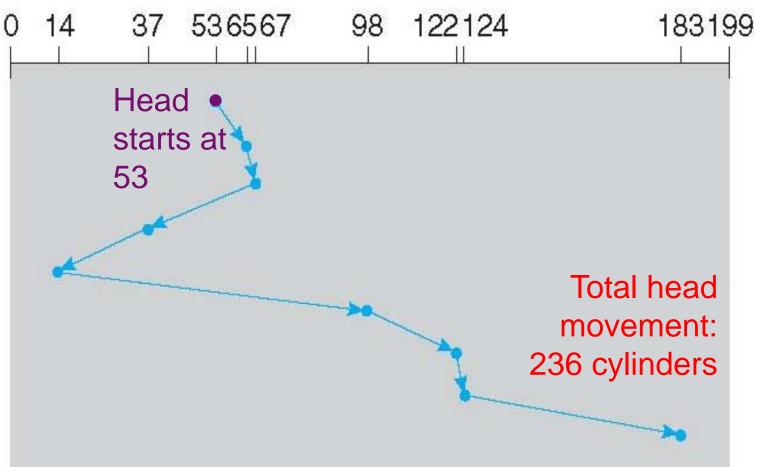


- FCFS serves accesses in order.
  - Given a set of accesses: 98, 183, 37, 122, 14, 124, 65, 67



## Shortest Seek Time First (SSTF) Algo.

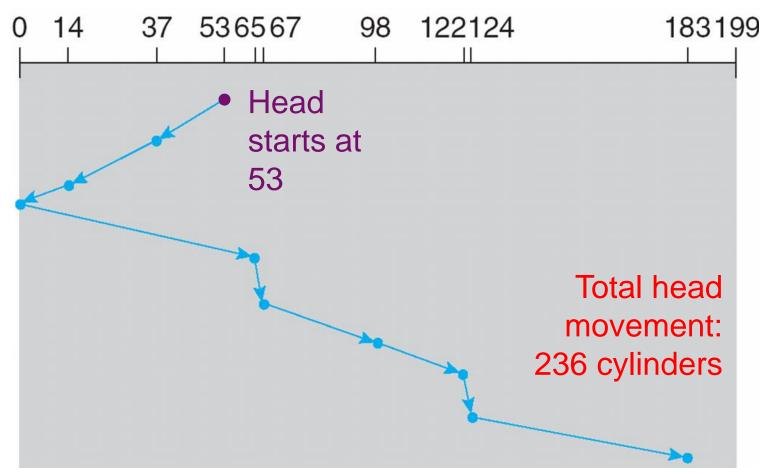
- **SSTF** selects the request with the minimum seek time from the current head position.
- Given accesses: 98, 183, 37, 122, 14, 124, 65, 67



### **SCAN/Elevator Algorithm**



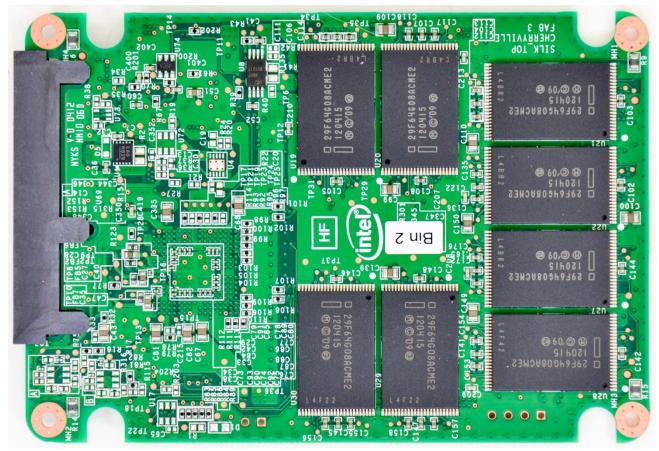
- SCAN starts at one end of the disk, moves toward the other end, reverses until reaching any end.
- Given accesses: 98, 183, 37, 122, 14, 124, 65, 67



# Solid State Drive (SSD)



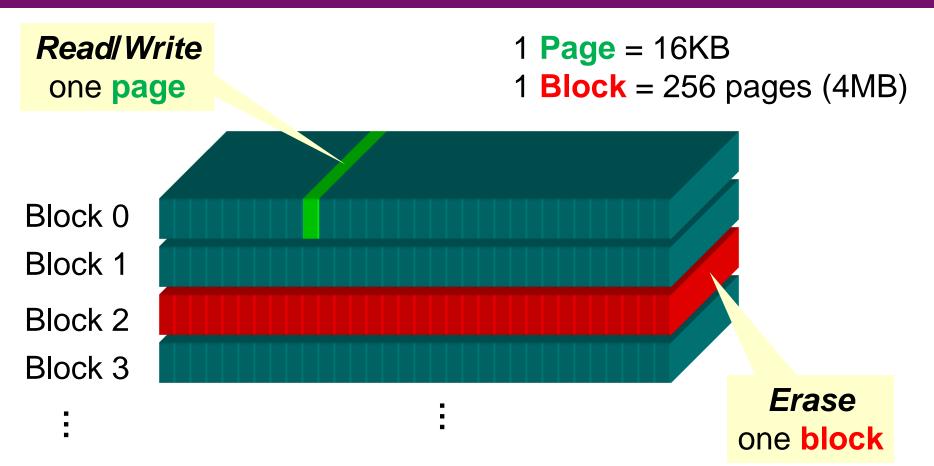
- SSD is made by NAND flash memory.
- Digital data can be accessed randomly on memory cells of SSD (without introducing seek time as HDD).



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#### **Flash Memory Characteristics**





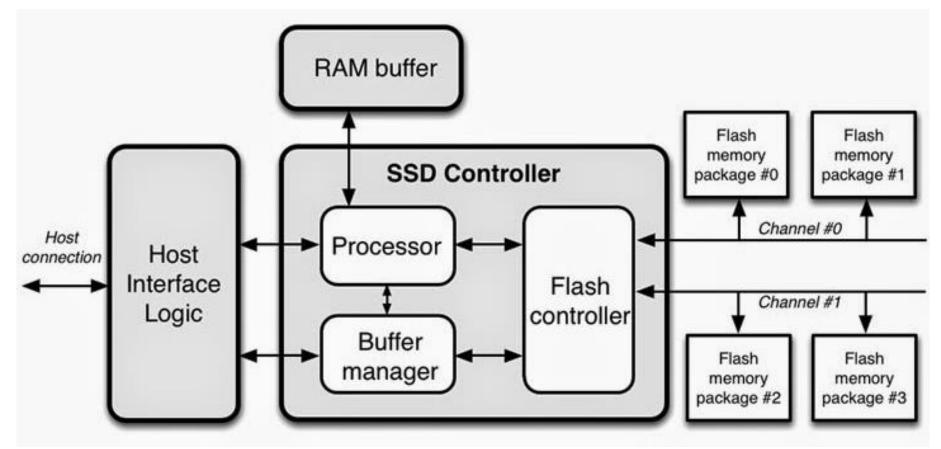
- Write-Once Property: Overwriting any page is not allowed unless its residing block is erased.
- Endurance: A block can be erased for a certain time.

#### **SSD Management**



• SSD internals require sophisticated management to deal with the flash memory characteristics.

– There is a processor inside the SSD.



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